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Evaluation of an Atmospheric Microclimate Model

by Arnold D. Tunick

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Abstract

Micrometeorological field data were used in an effort to evaluate an atmospheric microclimate model, specifically, to determine if we can forecast one-dimensional profiles of the atmospheric boundary layer sufficiently well that the corresponding outdoor acoustic field can be reliably calculated.

A soil-plant-atmosphere model was exercised with two sets of experimental data. The model was used to calculate the surface energy budget and to derive meteorological profiles for the overlying boundary layer; both of these were compared to field data. These modeled results were also used to derive outdoor sound-speed profiles and were used as input to a short-range acoustic propagation numerical code.

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1. Introduction

In the *Glossary of Meteorology* (Huschke, 1959), "microclimate" is defined as "the fine climate structure of the air space which extends from the very surface of the earth to a height where the effects of the immediate character of the underlying surface no longer can be distinguished from the general local climate (mesoclimate or macroclimate)." In modeling microclimate, one simulates the characteristics of the atmospheric surface and boundary layers. Its time-varying behaviors are related, albeit nonlinearly, to radiative heating and cooling, changes in water content of both the air and soil, terrain, land use, and ground cover. Numerical computer models attempt to simulate the microphysical processes of microclimate for a wide range of applications. In defense technology, microclimate data can be applied operationally, as well as in support of planning, environmental assessment, and research.

Several turbulence-diffusion, atmospheric boundary-layer models are presented in the literature, including those of Avissar et al (1986), Burk (1977, 1980), Blackadar (1978, 1979), Cionco (1965, 1985), Deardorff (1972, 1978), Mellor and Yamada (1974), Naot and Mahrer (1989), Pielke and Mahrer (1975), Yamada and Mellor (1975), and Zhang and Anthes (1982). With some proven measure of accuracy, they attempt to determine the temporal changes of specific meteorological quantities for different environments and sets of initial conditions. Many of these models represent sets of equations for two- and three-dimensional mesoscale (20 to 200 km domain) predictions over complex terrain.

This report documents an evaluation effort in which I studied a one-dimensional (1D) version of the plant-canopy microclimate model, as given by Avissar and Mahrer (1982, 1988), using two dissimilar sets of micrometeorological field data (Clarke et al, 1971; Stenmark and Drury, 1970). I made model calculations of the surface energy budget and compared them to field observations for both data sets. I also computed meteorological profiles for the overlying boundary layer, comparing these also to the observed field data. I used these modeled results to derive outdoor sound-speed profiles. The model output data were also used as input to the acoustic propagation numerical code WSCAFFIP (Noble, 1996; Noble and Marlin, 1995) for calculating levels of short-range acoustic attenuation. My goal was to determine if it was possible to forecast 1D profiles of the atmospheric boundary layer sufficiently well that the corresponding outdoor acoustic field could be reliably calculated. Time-dependent forecasts of microclimate processes are rarely used in atmospheric acoustics (Noble, 1991, 1992).

Following an overview of the soil-plant-atmosphere model (sect. 2), I describe the two evaluation data sets (sect. 3). Model results are discussed in section 4. I then present the derived sound-speed profiles and results from the acoustic propagation numerical code WSCAFFIP (sect. 5). Finally, conclusions are drawn (sect. 6) and recommendations related to this area of study are given (sect. 7).

2. Model Description

The 1D turbulence-diffusion model of the plant-canopy microclimate reported by Avissar and Mahrer (1988) is based on their earlier efforts (Avissar and Mahrer, 1982), as well as the earlier works of Deardorff (1978) and Pielke and Mahrer (1975). It is a simulation model that generates a fairly complex set of calculations at the soil and plant level, so that the surface energy budget (e.g., the transference of heat and moisture) can be made integral to processes within the first 1 to 3 km of the overlying atmosphere. Although the model was originally developed for applications in irrigation management by engineering estimates of actual and potential evapotranspiration (Avissar et al, 1986; Kordova et al, 1994), I revised it to yield time-dependent calculations of the atmospheric acoustic field that result as the derivative of modeled wind speed, wind direction, temperature, and humidity profile estimates.

As initial input, the model requires the numerical equivalent of the day of the year and the time of day (relative to the Greenwich meridian), site location data (latitude and longitude), fraction of sky cloudiness, and ground cover data (i.e., canopy height, leaf area index, surface reflectivity (albedo), thermal emissivity, and aerodynamic roughness length). The model computes soil properties (e.g., hydraulic and thermal conductivity and soil specific heat capacity) from inputs of soil water content, porosity, texture (i.e., proportion of sand, clay, and organic matter), and bulk density. Other model constants include subsoil properties, such as plant root density and distribution. Also, initially, the model requires profile data for air temperature and specific humidity (atmospheric water vapor content) from the ground level to the model top. Lastly, the screen level (2 m above ground level) values of wind speed, wind direction, temperature, and humidity are updated at each hour of the model run.*

The model's estimates of 1D profile structure are computed from a simplified set of kinematic and thermodynamic equations. The transference of momentum (i.e., effects of surface roughness and wind shear) and the exchanges of heat and moisture from one level to the next are calculated in terms of eddy coefficients and vertical gradients that represent the flux. The model turbulence-diffusion equations for momentum can be expressed as

$$\frac{\partial u}{\partial t} = f v - f v_g + \frac{\partial}{\partial z} \left(K_m \frac{\partial u}{\partial z} \right), \quad (1)$$

$$\frac{\partial v}{\partial t} = -f u + f u_g + \frac{\partial}{\partial z} \left(K_m \frac{\partial v}{\partial z} \right), \quad (2)$$

for the u - and v -components of wind speed, where f denotes the Coriolis parameter (the deflecting force due to the earth's rotation acting upon

*Although this model requires a tremendous amount of initial input as well as supporting data for updating calculations every hour, it may still be possible to apply it generally to locations worldwide. One could use bulk estimates of the soil thermal properties and plant or ground cover data, and hourly meteorological inputs (such as wind speed, temperature, or cloud cover) could be extracted from 3D mesoscale model forecasts run independently from the microclimate code.

moving air), the subscript g refers to the geostrophic wind (such that the second terms on the right represent the pressure gradient force), and K_m denotes the exchange coefficient for the diffusion of momentum. In the surface layer K_m is calculated as $K_m = ku_*z/\phi_m$, where k is Karman's constant (a dimensionless constant ($k = 0.4$) of atmospheric fluid dynamics), z is height (in meters), u_* is the friction velocity (in meters per second) that quantifies drag or surface stress, and ϕ_m is the nondimensional wind shear, which accounts for stability, turbulence, and near-ground wind speed profile structure (Monin and Obukhov, 1954; Businger et al, 1971; Dyer, 1974).

In the convective (heated), daytime boundary layer, the model derives the mixing coefficients as a function of height, as suggested by O'Brien (1970). The function can be expressed as

$$K_z = K_{z_i} + \left(\frac{(z_i - z)^2}{(z_i - z_s)^2} \right) \left(K_{z_s} - K_{z_i} + (z - z_s) \left[\frac{\partial K_{z_s}}{\partial z} + \frac{2(K_{z_s} - K_{z_i})}{z_i - z_s} \right] \right), \quad (3)$$

where z is height above ground level and the subscripts s and i refer to the heights of the top of the surface layer and top of boundary layer, respectively. The profile function K_z is applied similarly for the heat and moisture coefficients where for heat exchange $K_H = k\theta_*z/\phi_H$ and for moisture exchange $K_q = kq_*z/\phi_q$ for $z \leq z_s$, where θ_* and q_* are scaling variables that quantify the near-ground-level gradients (Rachele et al, 1995, 1996a) of temperature and specific humidity, respectively. The model defines $z_s = 0.04 z_i$ and sets $K_{z_i} = 1.0$ for $z \geq z_i$.

Finally, the growth and decay of the planetary boundary layer is calculated from an expression derived by Deardorff (1974), which can be stated as

$$\frac{dz_i}{dt} - w_{z_i} = \frac{1.8(w_*^3 + 1.1u_*^3 - 3.3u_*^2 f z_o)}{g \frac{z_i^2}{\theta_s} \frac{\partial \theta^\square}{\partial z} + 9w_*^2 + 7.2u_*^2}, \quad (4)$$

where w_{z_i} is the vertical velocity at z_i (assumed to be negligible or equal to zero, since time-dependent calculations of vertical velocities are not explicitly derived), z_o is the roughness length that characterizes the frictional effects of the land morphology and the type of ground cover, $\partial \theta^\square / \partial z$ is the vertical gradient of potential temperature (pressure scaled temperature) in the stable air immediately above the boundary-layer top, and finally the vertical velocity scaling variable, an implicit calculation of buoyancy, is defined as

$$w_* = [(-g/\theta)u_*\theta_*z_i]^{1/3} \quad (5)$$

where g is acceleration due to gravity.

The set of equations for calculations through the soil layer, surface layer, and plant canopy are also given by Avissar and Mahrer (1988). However, in this work I made substitutions based on previous work of Rachele and Tunick (1994) for the equations used to determine solar angles (Woolf, 1968), insolation (Meyers and Dale, 1983), and clouds (Haurwitz, 1945).

The surface energy budget is applied to three layers: the soil (including several thin sublayers); the vegetative canopy and the air throughout the canopy; and the thin (1 to 4 m) layer of air that extends above the canopy top (Avissar et al, 1986). Air temperature and water vapor content for each layer are derived as a result of energy and mass transfers within the system (including plant transpiration). The model also includes heat conduction and moisture diffusion equations for the soil layer, since soil wetness and surface temperature are possibly the two most significant factors determining the partitioning of the total available energy to the soil, evaporative, and sensible heat fluxes. The total available energy (i.e., the net radiative flux) is approximated as a function of transmission, terrain, land use, albedo, canopy leaf area characteristics, soil wetness, and soil thermal properties. The equations of the plant-canopy energy budget are given in table 1.

Table 1. Components of atmospheric surface layer and plant-canopy radiation and energy budget (Avissar and Mahrer, 1988).

Component	Equation	Definition of terms
Plant-canopy energy budget (Carson, 1987)	$R_N = C_H + E_v + S_G$	R_N = net radiative flux C_H = sensible heat flux E_v = evaporation heat flux S_G = soil heat flux
Short-wave radiation (insolation), R_S (Meyers and Dale, 1983)	$R_S = I_o T_R T_G T_W T_A \cos(Z)$	I_o = solar constant ($\approx 1367 \text{ W/m}^2$) T_i = transmission coefficients for Rayleigh scattering (R), absorption by permanent gases (G) and water vapor (W), and scattering due to aerosols (A) Z = solar zenith angle ($^\circ$)
Sky long-wave radiation, $R_{L\downarrow}$	$R_{L\downarrow} = \sum_{z=0}^{\text{model top}} (\epsilon \sigma T_z^4)$	σ = Stefan-Boltzmann constant ($5.6697 \times 10^{-8} \text{ W m}^{-2} \text{ K}^{-4}$) T_z = air temperature (K) $\epsilon = \epsilon_{\text{H}_2\text{O}} + \epsilon_{\text{CO}_2}$ = total emissivity $\epsilon_{\text{H}_2\text{O}}$ = emissivity of water vapor ϵ_{CO_2} = emissivity of carbon dioxide
Net radiation of canopy, R_{NV}	$R_{NV} = \psi_f (1 - \alpha_v)$ $\{1 + \alpha_g [1 - \psi_f (1 - t_v)]\} R_s + \psi_f \epsilon_v$ $\{[1 + (1 - \psi_f)(1 - \epsilon_g)] R_{L\downarrow} + \epsilon_g \sigma T_g^4\}$ $- \epsilon_v \sigma T_v^4 [2 - \epsilon_v \psi_f^2 (1 - \epsilon_g)]$	ψ_f = shielding factor (full canopy = 1; bare soil = 0) α_v = albedo of plant surface α_g = albedo of soil surface (albedo = reflectivity) t_v = transmissivity of the canopy ϵ_v = plant foliage emissivity ϵ_g = soil emissivity T_g = air-ground temperature (K) T_v = canopy virtual temperature that accounts for effects of moisture in air (K)

Table 1. Components of atmospheric surface layer and plant-canopy radiation and energy budget (Avisar and Mahrer, 1988) (cont'd).

Component	Equation	Definition of terms
Net radiation at ground, R_{NG}	$R_{NG} = (1 - \alpha_g)(1 - \psi_f + \psi_f t_v)R_s$ $+ (1 - \psi_f)\epsilon_g R_{L\downarrow} + \psi_f \epsilon_g \epsilon_v \sigma T_V^4$ $- \epsilon_g \sigma T_g^4 [1 - \epsilon_g \psi_f (1 - \epsilon_v)]$	R_s = short-wave radiation, insolation (W/m^2)
Sensible heat, C_H	$C_H = C_{HV} + C_{HG}$	
Sensible heat between canopy and air, C_{HV}	$C_{HV} = \psi_f^* \rho c_p u_* \theta_*$	$\psi_f^* = \frac{\text{flux of canopy}}{\text{total flux of canopy + soil}} = \frac{2A_L \psi_f}{1 + 2A_L \psi_f}$ A_L = leaf area index ρ = density of air (kg/m^3) c_p = specific heat of air (J/kgK) u_* = surface friction velocity (m/s) θ_* = surface scaling temperature (K)
Sensible heat between ground and air, C_{HG}	$C_{HG} = (1 - \psi_f^*) \rho c_p u_* \theta_*$	
Evaporation flux, E_V	$E_V = E_{VV} + E_{VG}$	
Evaporation flux between canopy and air, E_{VV}	$E_{VV} = \psi_f^* \rho L^* u_* q_*$	L^* = heat of vaporization or condensation (J/kg) q_* = surface scaling specific humidity (g/g)
Evaporation flux between ground and air, E_{VG}	$E_{VG} = (1 - \psi_f^*) \rho L^* u_* q_*$	
Soil heat flux, S_G	$S_G = -\lambda \frac{\partial T_g}{\partial z}$	λ = soil thermal conductivity ($W m^{-1} K^{-1}$; derived in terms of soil composition and soil wetness)
Heat conduction	$c_s \rho_s \frac{\partial T_g}{\partial t} = \frac{\partial}{\partial z} \left[\lambda \frac{\partial T_g}{\partial z} \right]$	c_s = soil specific heat ($J m^{-3} K^{-1}$) ρ_s = soil density ($kg m^{-3}$)
Soil moisture diffusion (Naot and Mahrer, 1989)	$\frac{\partial \Delta}{\partial t} = \frac{\partial}{\partial z} \left[D_\Delta \frac{\partial \Delta}{\partial z} \right] + \frac{\partial}{\partial z} \left[D_T \frac{\partial T_g}{\partial z} \right]$ $+ \frac{\partial K_h}{\partial z} - L_{PT}$	Δ = soil water content (%) D_Δ = isothermal moisture diffusivity D_T = thermal moisture diffusivity K_h = hydraulic conductivity (m/s) L_{PT} = soil water loss through plant transpiration

3. Field Data

3.1 Hay 1967

One of the sets of experimental data used in this study was collected during a field campaign near the town of Hay, New South Wales, Australia (34.50, 144.93), which took place during the 1967 southern hemisphere winter, from 15 July to 27 August (Clarke et al, 1971). This very large data set was collected over an extensive flat area (3600 km²), where the ground cover was predominantly sparse low vegetation over dry soil. For the task at hand (model verification with regard to surface-layer and overlying boundary-layer profile structure), the data were highly suitable in all areas except for plant-canopy interactions. Five types of surface-layer and mixed-layer data were collected: (1) hourly 16-m micrometeorological tower measurements of wind speed, specific humidity, and temperature; (2) hourly surface measurements of the net radiative balance and soil heat flux; (3) measurements of wind speed and wind direction from 0 to 2 km (AGL—above ground level) obtained by hourly pibal (pilot balloon) flights; (4) measurements of pressure, temperature, and mixing ratio ($m_r = \text{mass}_{\text{water vapor}} / \text{mass}_{\text{dry air}}$), to a height of 2 km, taken by radiosonde (instrumented balloon sonde) flights at 3-hr intervals; and (5) reports of fractional, low, high, and total cloud cover (including cloud type descriptors).

Of the 1050 hourly reports (profiles) of published observations, I used those collected during the 27-hr period from 2100 LT (local time) on 15 August 1967 to 2400 LT on 16 August 1967. This data-collection period was characterized by clear skies and relatively light daytime wind speeds. Dry soil promoted strong surface-based convective heating. The soils for the field area were predominantly brown loams overlying red-brown clay subsoils.

3.2 Davis 1966

The second set of experimental data used in this study was collected during a field study at Davis, California (38.33, 121.44), during the summer of 1966 and spring 1967 (Stenmark and Drury, 1970). The field site was a flat, fescue-grass-covered 50,000-m² area at 17-m elevation (above mean sea level). It was about 2 km west of the main portion of the University of California at Davis campus, 113 km northeast of San Francisco. The data were taken during periods when fields surrounding the test area were for the most part crop covered and well irrigated, giving (in effect) horizontal uniformity to the surface conditions with respect to temperature and moisture. Advection effects due to the site's proximity to the coast were considered to be negligible during the data-collection period. Profiles of wind speed, temperature, and specific humidity were taken at nine levels from 25 to 600 cm. In addition, infrared radiometers, ground heat flux plates, and a large (3.0-m-diameter) weighing lysimeter were used to record the net radiation, the soil heat flux, and surface evaporation rates, respectively. The energy budget equation was used to determine the sensible heat flux

C_H as the residual. The soils at the Davis field site were predominantly silt loams.

In the present study, I used the 30-hr subset of data taken from 0100 LT on 13 July 1966 to 0600 LT on 14 July 1966. This data interval was characterized by clear skies, damp soil, low wind speeds through the morning, and moderate wind speeds through the afternoon. Increased evaporation rates associated with the change (increase) in surface wind speeds were observed. (The surface wind direction (190° to 210°) remained, for the most part, constant.) The data collected from this site were very well suited for verifying the model with regard to surface-layer energy budget calculations.

3.3 Model Parameters from Data Sets

Table 2 gives model parameters for both the Davis 1966 and Hay 1967 data sets. Typical values given for albedo and surface roughness for other combinations of soils and ground cover can be retrieved from Hansen (1993a, 1993b). Hourly meteorological input for both data sets is given in tables 3 and 4.

Table 2. Model parameters for Hay 1967 and Davis 1966 data sets.

Variable name	15–16 August 1967 Hay, Australia	13–14 July 1966 Davis, CA
Latitude	34.50 S	38.33 N
Longitude	144.93 E	121.44 W
Albedo	0.20	0.27
Emissivity	0.98	0.96
Roughness length	0.13 cm	1.40 cm
Ground cover/canopy height	barren field/0.0 cm	dense field/10.0 cm
Leaf area index	0.0	1.0
Soil properties:		
Water content	0.08 %	0.20 %
Thermal conductivity	$0.539 \text{ W m}^{-1} \text{ K}^{-1}$	$0.947 \text{ W m}^{-1} \text{ K}^{-1}$
Volumetric specific heat	$1.374 \text{ J m}^{-3} \text{ K}^{-1}$	$1.887 \text{ J m}^{-3} \text{ K}^{-1}$
Density	1400.0 kg m^{-3}	$\approx 1400.0 \text{ kg m}^{-3}$
Soil texture:		
% sand	28.0	20.0
% clay	70.0	77.0
% organic	2.0	3.0

Table 3.
Meteorological model
input (1-hr average
data) for Hay 15–16
August 1967 data set
(winter).

Local time	Temperature (°C)	Specific humidity (g/kg)	Wind speed (m/s)	Wind direction (°N)
21	5.4	4.818	1.75	165
22	4.0	4.266	1.67	155
23	3.3	4.295	1.39	156
24	2.8	4.190	1.57	160
1	2.2	4.058	1.71	160
2	2.2	4.058	2.18	162
3	1.7	3.957	2.03	159
4	0.6	3.693	1.67	159
5	-0.3	3.495	0.77	158
6	-0.3	3.531	0.40	155
7	-0.4	3.506	0.40	142
8	0.9	3.774	1.21	138
9	5.3	4.893	2.71	107
10	9.2	5.768	2.41	89
11	11.7	6.241	2.23	113
12	12.7	6.311	2.62	102
13	13.3	6.380	1.90	116
14	13.8	6.401	2.91	127
15	14.2	6.472	2.85	108
16	14.6	6.543	3.62	111
17	14.6	6.440	3.04	94
18	12.3	6.057	1.61	105
19	8.1	5.217	2.06	119
20	6.5	4.848	1.64	120
21	5.6	4.664	1.79	111
22	4.3	4.256	1.39	104
23	2.8	4.008	1.80	103
24	2.6	3.951	1.81	98

Table 4.
Meteorological model
input (30-min average
data) for Davis 13–14
July 1966 data set
(summer).

Local time	Temperature (°C)	Specific humidity (g/kg)	Wind speed (m/s)	Wind direction (°N)
1	12.81	8.08	1.800	154
2	12.46	8.03	1.839	146
3	12.08	7.96	1.239	167
4	11.96	7.92	0.313	167
5	11.46	7.69	0.516	145
6	12.74	8.14	1.648	299
7	15.03	8.48	1.934	327
8	17.21	9.12	1.845	336
9	19.21	9.63	1.629	276
10	20.63	10.11	1.939	194
11	22.61	10.22	1.408	210
12	23.88	10.11	2.865	218
13	25.12	9.92	3.247	208
14	25.85	9.33	5.026	192
15	25.84	8.67	5.932	206
16	25.12	8.24	5.738	218
17	23.40	8.16	5.429	210
18	21.87	8.10	5.151	204
19	18.85	7.72	4.403	206
20	16.48	7.30	4.582	210
21	14.46	7.47	3.177	208
22	13.50	7.46	2.723	204
23	13.19	7.50	3.686	205
24	12.82	7.49	3.996	210
1	12.43	7.67	3.966	204
2	11.87	7.47	3.739	198
3	11.68	7.44	3.432	200
4	11.51	7.35	3.979	192
5	11.34	7.27	2.923	194
6	12.56	7.6	1.902	240

4. Model Results

4.1 Surface Energy Budget

Figure 1 shows computations for two components of the surface energy budget (net radiation and soil heat flux) for the Hay data set, along with field data. The calculated and observed data appear well matched. As these results show, the model is generally effective in computing radiative exchanges over near-barren ground and heat transfer through a dry soil layer.

On the other hand, ground temperature approximations (not shown) were somewhat underestimated, as much as 1 to 3 °C, particularly during the night and early morning hours before sunrise. Had the predicted surface temperatures been more in line with the observed data for those times, the calculated value for the outgoing soil flux would have been higher. Often, discrepancies of this kind between data and model output can be minimized by a process of iterative “tuning” (i.e., adjustments made within justifiable limits) of just a few specific input parameters, such as soil water content, albedo, or surface roughness, for example. In this case, however, the model was relatively unresponsive to this kind of tuning.

Figure 2 shows estimates of the surface energy budget for the Davis 1967 data set. The model calculations agree remarkably well with the observed data for the net radiative flux and the evaporative flux above the irrigated canopy layer. The sensible heat and soil heat fluxes, however, do not agree as well with the observed data as would have been expected considering the other computed results. In previous work with this data set (Rachele and Tunick, 1994; Rachele et al, 1996b), it was found that increased wind speeds beginning from 1300 to 1400 LT (see table 4) were catalysts for higher rates of evaporation, drawing heat from the air in the layer adjacent to the canopy, and promoting increased surface layer stability. In the model calculations reported here, however, the sensible cooling of the air did not seem to take place as I would have expected. Figure 2 shows a nearly 3-hr time difference where $C_H = 0.0 \text{ W/m}^2$. The modeled excesses in the sensible heat flux suggests that the calculated surface temperatures (not shown) may have been too high. These surface layer processes, by the

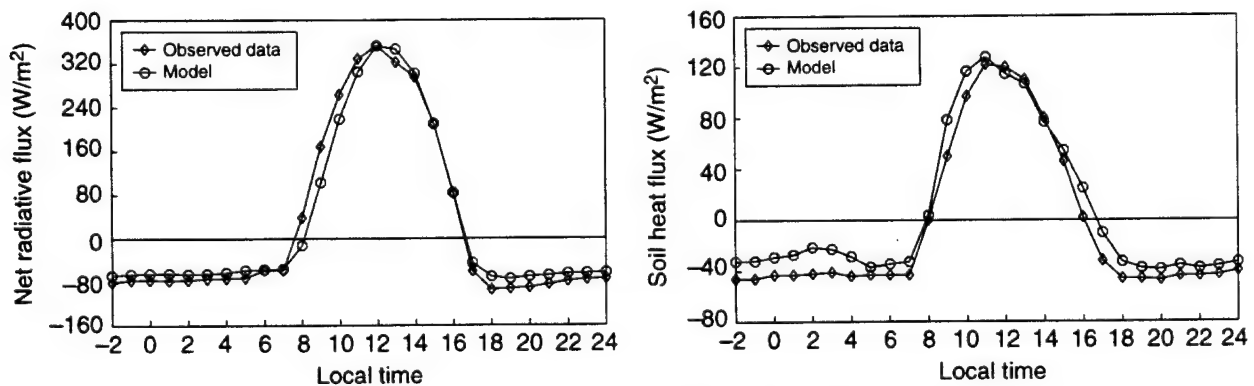


Figure 1. Model comparisons to observations of net radiative flux (left) and soil heat flux (right) for Hay 1967 data set.

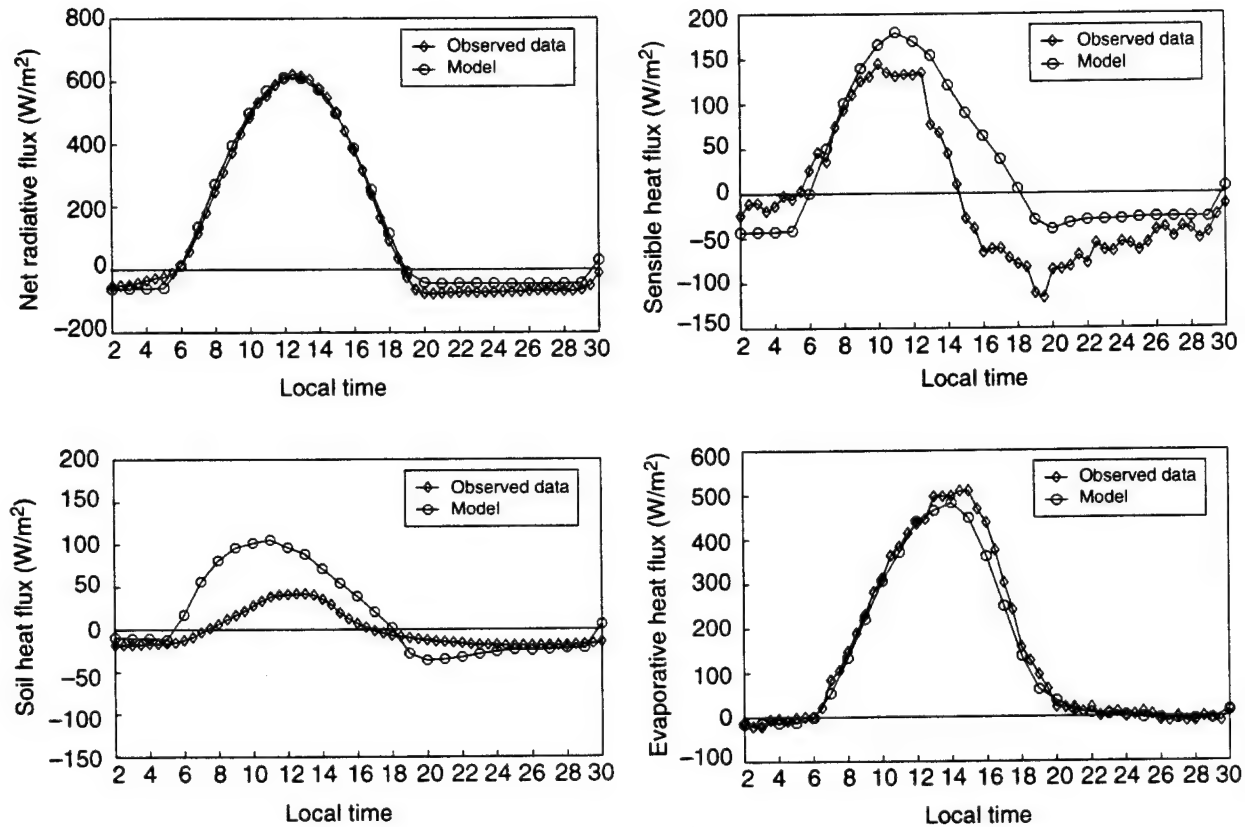


Figure 2. Model comparisons to observations of net radiative flux (top left), sensible heat flux (top right), soil heat flux (bottom left), and evaporative heat flux (bottom right) for Davis 1966 data set.

definition of microclimate, affect the structure of temperature, wind speed, and humidity profiles through the overlying boundary layer (as I show in sect. 4.2).

4.2 Boundary-Layer Profile Structure

From the boundary-layer data collected at Hay, I studied 6- and 18-hr forecasts in order to evaluate the microclimate model with regard to mixed layer profile structure. Figure 3 shows modeled and recorded air temperature and specific humidity profiles. The model output agrees with many of the gross features of the observed data: for example, the simulated nighttime temperature inversions (top left) appear to be captured by the model, even though the intensities of the near-surface and upper-level gradients differ. The computed temperature profiles for the daytime case (top right) also appear to be in agreement with observed data; however, the temperature profile gradients at the top of the boundary layer are clearly offset (see fig. 4). On close inspection, the model and observed daytime temperature surface gradients are offset as well.

**As a matter of convention, for the net radiative and soil heat flux, positive values represent energy transferred downward, while negative values represent energy transferred away from the soil–plant–atmosphere interface. The opposite is an accepted convention for the sensible and evaporative heat fluxes.*

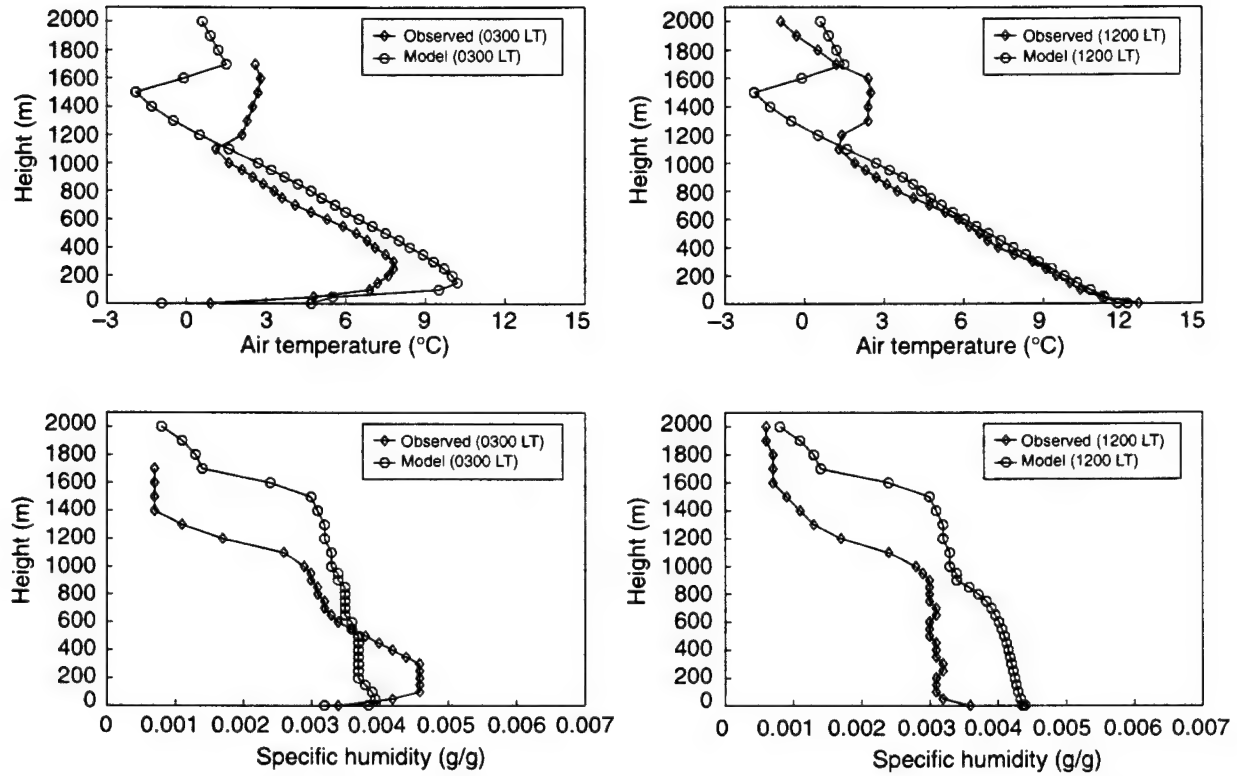
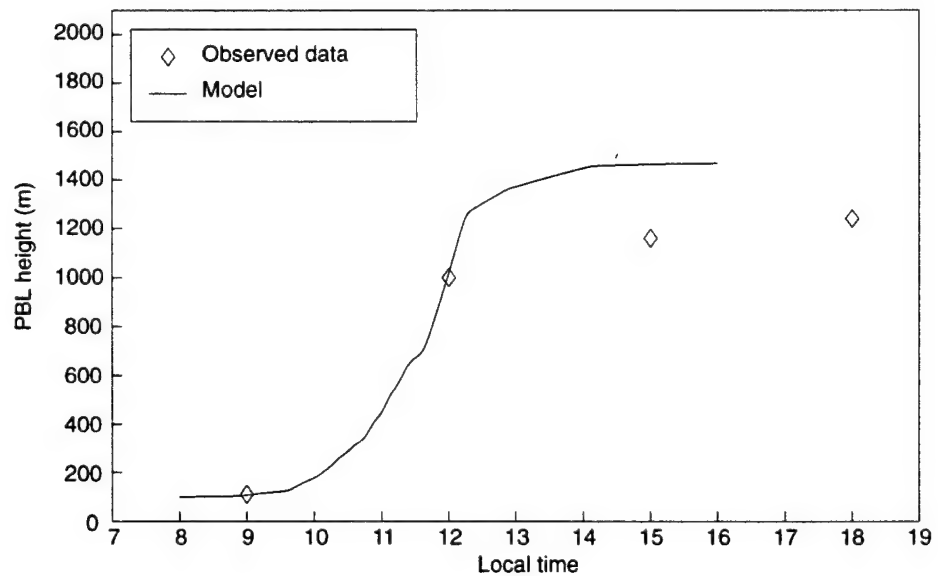


Figure 3. Model comparisons to observations of profiles of boundary-layer temperature (top) and specific humidity (bottom) for Hay 1967 data set.

Figure 4. Model comparison to observations of depth of planetary boundary layer for Hay 1967 data set.



The simulated specific humidity profiles in figure 3 (bottom) show offsets in water vapor content through the upper and lower levels of the boundary layer, in contrast to the observed data. The observed data indicate a characteristic drying out of the lower atmosphere due to vertical mixing. Alternatively, the modeled profiles indicate tendencies toward an overall increase of boundary layer moisture over this period of time.

By definition, mixing depths are determined as a function of boundary-layer growth and decay. These processes, in general, are driven by the radiative exchanges that govern the surface heat and moisture budget. Therefore, discrepancies between predicted and observed inversion heights are most often due to the inaccuracy of the predicted surface-layer gradients. Otherwise influences on boundary-layer growth must be attributed to external and upper-level forcings, such as advection or changes in the large-scale horizontal pressure gradient. The unmatched inversions shown in figure 3 are then most likely the result of overpredicted surface-layer heating. This was found to be the case in an earlier study that was repeated by Pielke and Mahrer (1975) using the prediction expression of Deardorff (1974) (eq (4), sect. 2, this report). Values of calculated mixed-layer heights, shown in figure 4, compared to those determined from observations are given in table 5.

Figure 5 shows model-derived wind speed and wind direction. The 1D model predicts an observed, nighttime wind speed maximum (left) very poorly. It also fails to match fluctuations in the observed daytime wind speed profile (right) although on average, the mean differences are less than 1 m/s.

Diurnal accelerations and decelerations in wind speed are normally due to changes in mesoscale pressure gradients (over a range of 20 to 200 km). These gradient changes are brought about by changes in temperature near the ground, which increase or decrease aerodynamic drag and stress (McNider and Pielke, 1981). To model these processes adequately, one would need time-dependent, 3D, horizontal and vertical transfer equations for momentum, mass, and temperature for each point in a user-defined grid. From the results of this study, it becomes apparent that the 1D approach is not sufficient.

The forecasts of wind direction profile structure shown in figure 5 (bottom) are also poor through the forecast period, even though mean differences may appear to be on the order of $\pm 15^\circ$. It is known that wind directions are probably the most difficult variable for meteorological simulation models

Table 5. Calculated heights of planetary boundary layer compared to observations.

Local time	Height of boundary layer (m)	
	Observed data ^a	Model
0800	—	100.00
0900	110.00	107.36
1000	—	175.20
1100	—	439.79
1200	1000.00	1018.05
1300	—	1373.03
1400	—	1448.27
1500	1160.00	1464.05
1600	—	1468.23
1700	—	100.00
1800	1240.00	100.00

^aEstimated from observed potential temperature and specific humidity profile data (Pielke and Mahrer, 1975).

to predict. Events on a number of different scales, from frontal passages to local urban or rural land use, affect wind direction. Assessments of predicted wind direction have shown tremendous scatter compared to observations (see fig. 13.2 in Gross, 1994). However, next to temperature and changes in temperature with height, wind speed and direction are significantly important in assessing the outdoor acoustic field that results as a derivative of a microclimate forecast. The last sections of this report discuss the assessment of outdoor acoustic fields in greater detail.

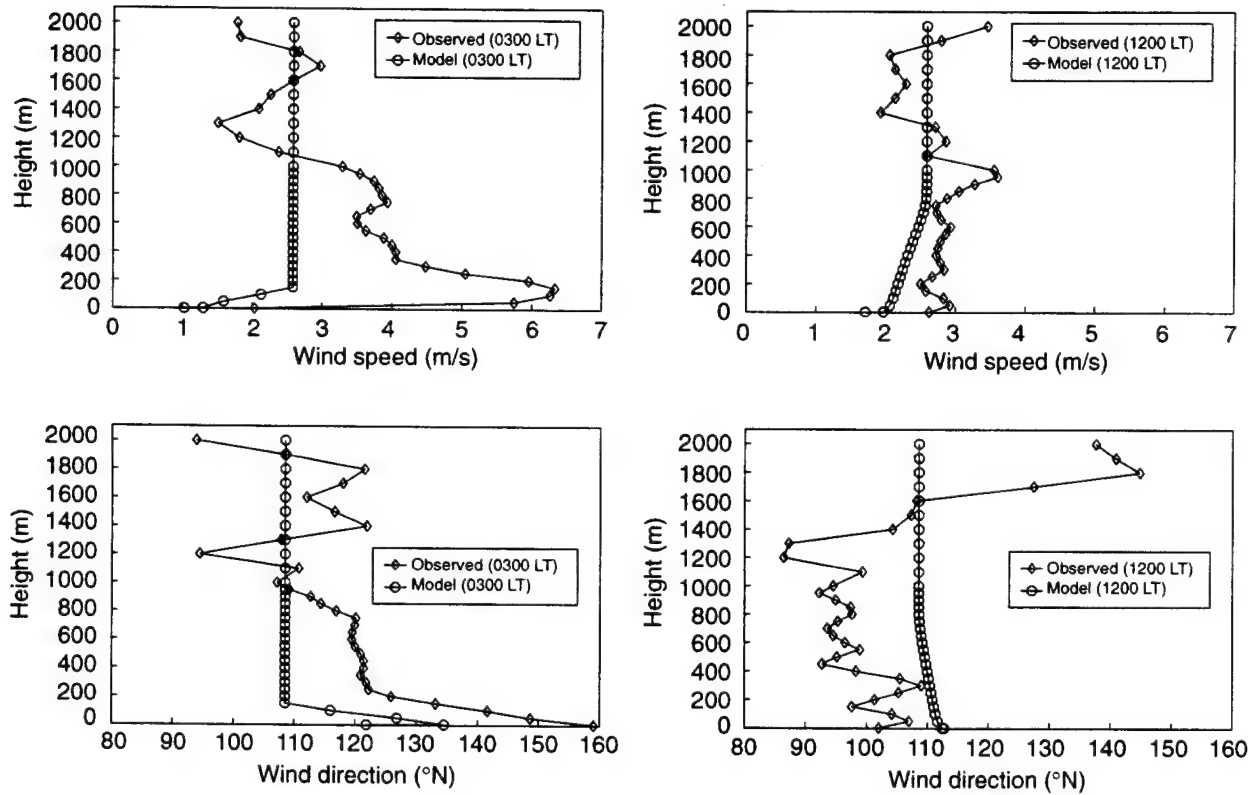


Figure 5. Model comparisons to observations of profiles of boundary-layer wind speed (top) and wind direction (bottom) for Hay 1967 data set.

5. Application to Atmospheric Acoustics

5.1 Calculated Boundary-Layer Sound-Speed Profiles

First-order approximations of sound speed in the absence of wind can be derived from the expression in Pierce (1981) given as

$$C(T) = \sqrt{\frac{\gamma RT}{M}} , \quad (6)$$

where γ is the ratio of the specific heats of air for constant pressure and constant volume modified to account for water vapor content so that $\gamma = (7 + h)/(5 + h)$, where h is the fraction of water molecules in the air, R is the universal gas constant ($8314.16 \text{ kg}^{-1} \text{ K}^{-1}$), T is air temperature in kelvins, and M is molecular weight, calculated as $M = 29 - 11h$. However, the variations of sound speed caused by even extreme changes in humidity are minimal (approximately 1 to 2 m/s) and can generally be ignored (Noble and Marlin, 1995). The effect of winds on sound speed is expressed by a vector relation. Equation (6) can be rewritten as

$$C_{eff}(z) = C(T) + U \cos(\theta_w - \pi - \theta_R) . \quad (7)$$

where $C(T)$ is the sound speed in the absence of wind at temperature T , U is the mean horizontal wind speed (in meters per second), θ_w is the wind direction (conventionally interpreted as the direction from which the wind originates), $\theta_w - \pi$ is interpreted as the along-wind direction, and θ_R is the azimuth or bearing of an outlying receiver from a given acoustic source. The environmental effects on the propagation of acoustic energy, as reviewed by Noble (1992), are related to the height-dependent variations of the sound-speed profile, which, in general, cause (1) upward refracting conditions, when the sound-speed gradients through the first 0 to 400 m of the mixed layer are negative (normally occurring during the day), or (2) downward refracting conditions, when the sound-speed gradients are positive (normally occurring at night).

Figure 6 shows the derived boundary-layer sound-speed profiles for the nighttime and daytime cases. There appears to be reasonably good agreement between the sound-speed profiles derived from model calculations and those derived from the field data, particularly for the daytime case shown. Differences between the results are principally related to the combined accuracy of simulated gradients in temperature and wind-speed profile structure. (It is only by a matter of convention that the calculations in the bearing $\theta_{surface}$ (left) are called upwind, while those made in the bearing $\theta_{surface} - 180^\circ$ (right) are called downwind.)

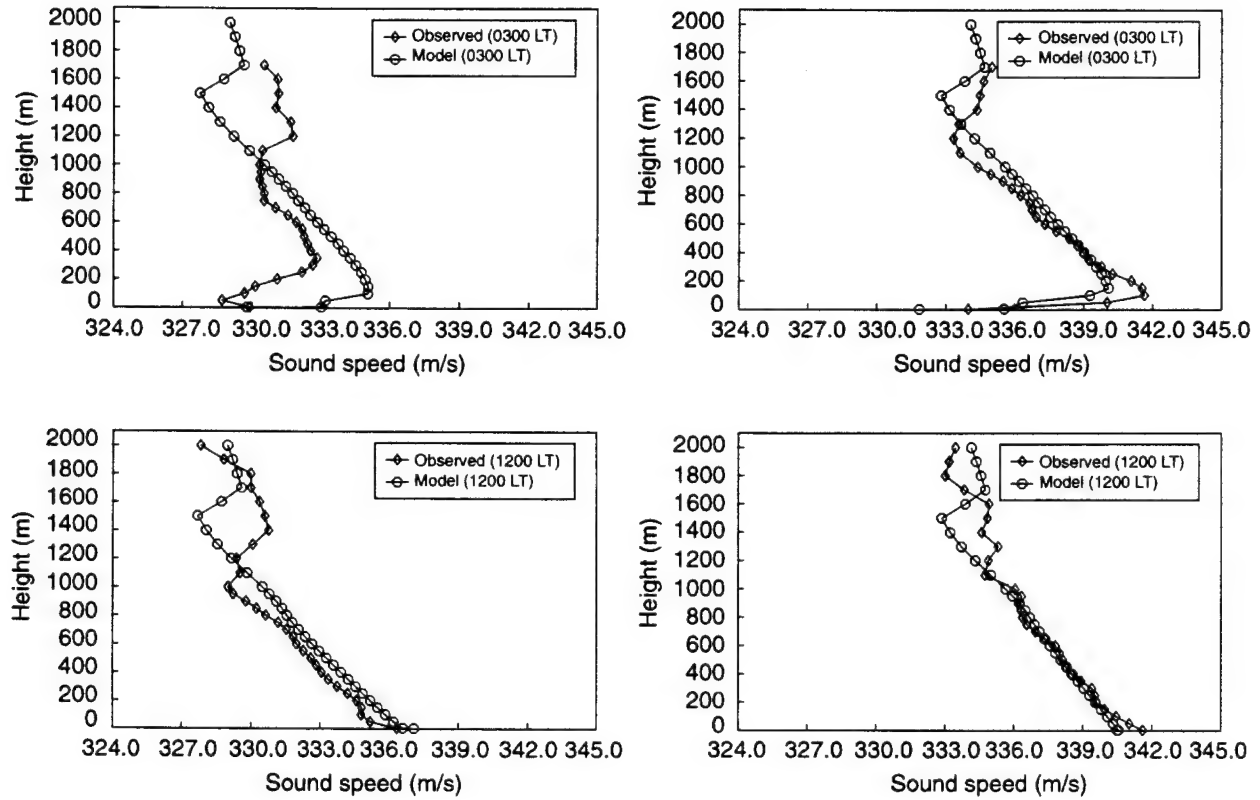
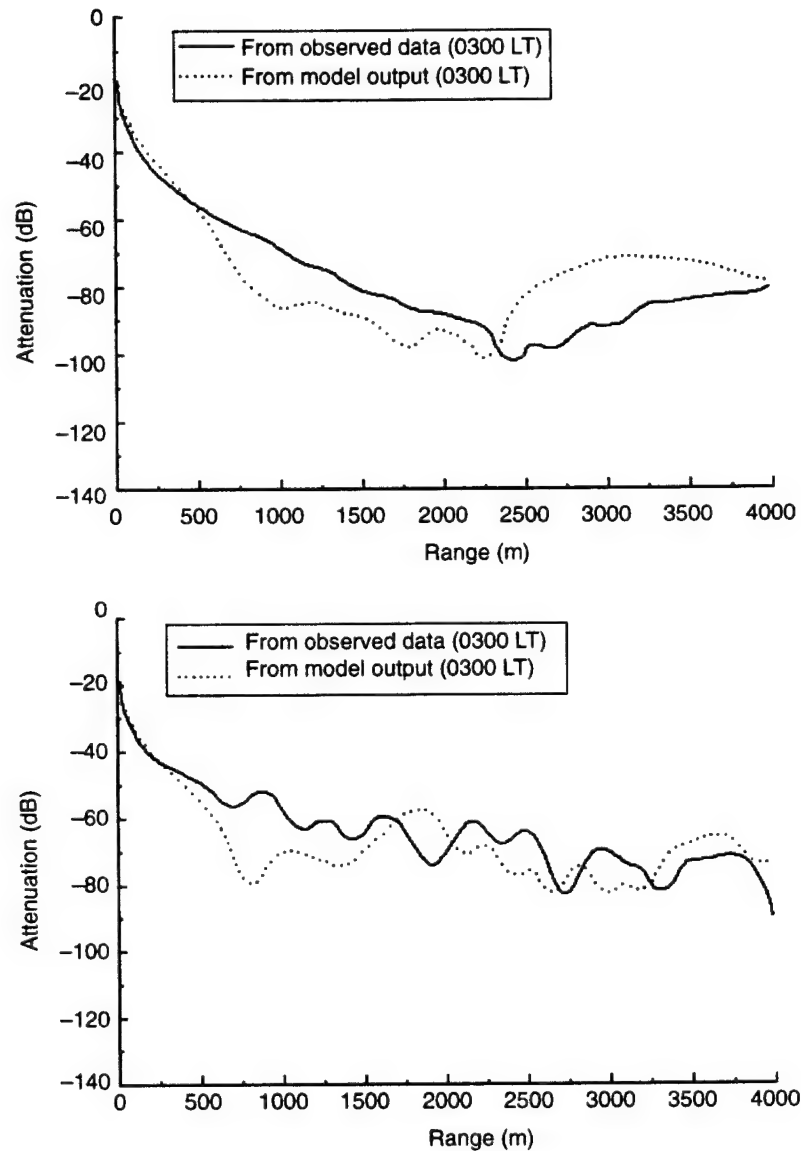


Figure 6. Derived boundary-layer sound-speed profiles for nighttime (top) and daytime (bottom) atmospheric conditions.

5.2 Approximations of Short-Range Outdoor Acoustic Attenuation

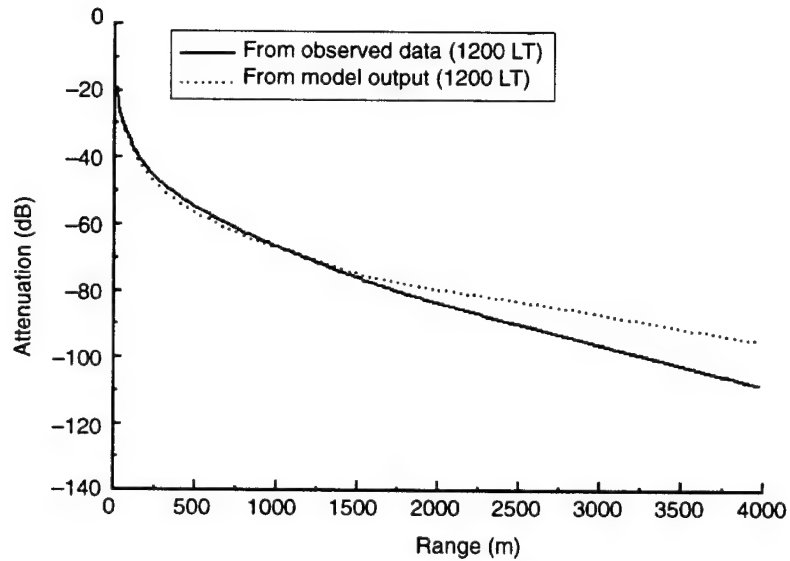
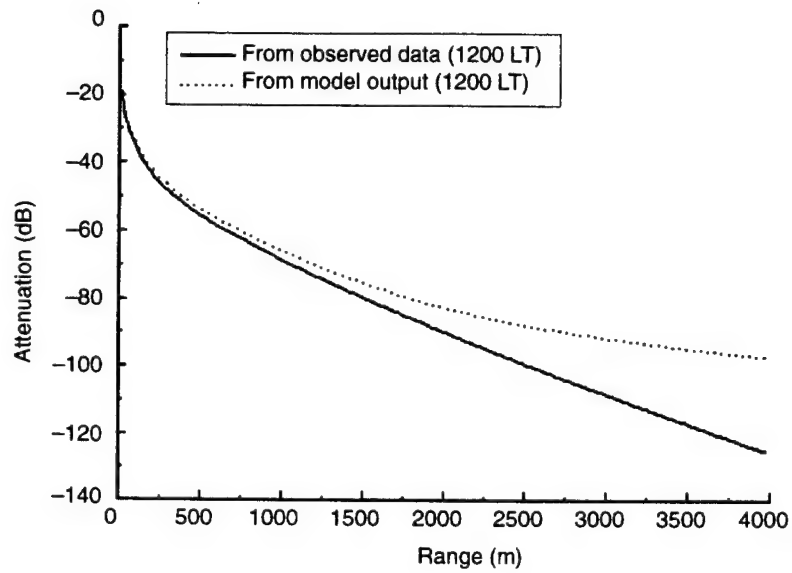
Meteorological profiles from observed Hay field data and those forecast by the model in this study were used as input to the acoustic propagation numerical code WSCAFFIP (Windows (version) Scanning Fast Field Program), which assesses environmental effects on short-range acoustic attenuation. WSCAFFIP provides attenuation levels with range and azimuth for a given geometry and frequency (Noble, 1996; Noble and Marlin, 1995). The acoustic propagation algorithms in WSCAFFIP attempt to represent the effects of atmospheric refraction, diffraction, absorption, and reflection or ground impedance. Figure 7 shows the WSCAFFIP results for the upwind (top) and downwind (bottom) nighttime cases. Ahead of the first segment of the data (i.e., $x \leq 650$ m), the calculated attenuation levels appear to be well matched. Further out in range, differences in the derived sound-speed profile gradients have resulted in either sound-limited areas (shadow regions) or areas of refocusing due to refraction (i.e., the local minima and maxima). As a rule, the more positive the sound-speed gradient (see fig. 6 (top)), the greater the effects of a downward refracting atmosphere, especially in the case of calculations made in the downward direction.

Figure 7. Short-range acoustic attenuation upwind (top) and downwind (bottom) predicted by WSCAFFIP numerical code for nighttime atmospheric conditions.



In contrast, the attenuation levels for the daytime case (fig. 8) show the effects of upward refracting atmospheric conditions. The amount of attenuation appears to be, overall, greater than in the nighttime case. Sound levels are shown to be in good agreement to a distance of approximately 1750 m in range. Beyond 1750 m, offsets in the profiles predictions have affected the degree of separation in the data, as seen in both figures in the range from 2000 to 4000 m.

Figure 8. Short-range acoustic attenuation upwind (top) and downwind (bottom) predicted by WSCAFFIP numerical code for daytime atmospheric conditions.



6. Conclusions

In the work reported here, I used micrometeorological field data in an effort to evaluate an atmospheric microclimate model. I set out to determine if it was possible to forecast 1D profiles of the atmospheric boundary layer sufficiently well that the corresponding outdoor acoustic field could be reliably calculated.

Specifically, I studied a soil-plant-atmosphere model using two dissimilar sets of experimental data: Hay 1967 and Davis 1966. Model calculations of the surface energy budget were compared to field observations. Derived meteorological profiles for the overlying boundary layer were also compared to data. Using these modeled results, I derived outdoor sound-speed profiles. I also used the modeled results as input to the short-range acoustic propagation numerical code WSCAFFIP.

Some general conclusions with regard to the evaluation of this atmospheric microclimate model follow.

1. Quantitative assessments of the surface energy budget over land principally rely upon equations sensitive to variations in soil wetness and surface temperature, since these are probably the two factors most significant determining the partitioning of the soil, evaporative, and sensible heat fluxes.
2. As shown by the results of the surface energy budget calculations with the Hay 1967 field data used as input, the model is, overall, effective in computing radiative exchanges over sparsely covered ground and heat transfer through a dry soil layer.
3. Discrepancies between data and model output can normally be minimized by a process of iterative "tuning" of just a few specific input parameters, such as soil water content, albedo, or surface roughness. For the case with the Davis 1966 data used as input, however, the model was relatively unresponsive to this kind of tuning. Therefore, although the radiative and evaporation flux calculations for the irrigated canopy were in good agreement with the field data, the sensible and soil heat fluxes agreed less well with the observed data than I had expected.
4. The 1D forecasts of meteorological profile structure in the atmospheric boundary layer were generally very poor, especially with regard to windspeed. This level of model performance was disappointing. The 1D approach appears to be insufficient to effectively represent effects of surface roughness, wind shear, and the exchanges of heat and moisture from one level to the next.
5. Quantitative assessments of the outdoor acoustic field rely upon accurate representations of the local meteorology, since variations in the profile gradients of sound speed are determined from these data. Therefore, the discrepancies in the forecasts of short-range acoustic attenuation with range presented in this study were most likely due to sufficiently significant offsets in the profiles of sound speed, particularly in the 0 to 400 m layer above ground.

7. Recommendations

The components of the atmospheric surface energy budget, by definition, reflect the rates of heating and cooling near the ground. The transfer of incident, reflected, and emitted energy at the surface can be approximated as functions of cloud cover, terrain roughness characteristics, surface albedo, canopy leaf area, soil water, and soil thermal capacities. As an integral part of the microclimate, the surface energy budget acts as the principal influence on the development of pressure, temperature, and humidity gradients on all scales. As a result, most of the turbulence and diffusion of heat, momentum, and moisture in the boundary layer can be attributed to surface layer energy exchanges. They are inherently multidimensional processes.

In recent years, however, several efforts have relied on 1D meteorology for defense-related applications, in particular, outdoor acoustics. Both models and measured field data have been manipulated in efforts to create reliable product codes. Unfortunately, at the conclusion of each initiative, it is found that better assessments or forecasts of wind, temperature, and humidity fields require further research (into models that can account for changes in the state variables over time, both horizontally and vertically, from within as well as from outside the modeling area of interest). The 1D approach applied to areas 10 to 80 km across has been insufficient, especially with regard to estimates of wind speed and wind direction. In application, only limited successes have been realized. Therefore, because of their explicit dependence on temperature and wind profile structure, acoustic attenuation models, especially, need to incorporate 3D meteorological data (or forecast fields). Their reliability in the battlefield environment would then, in my opinion, greatly improve.

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